

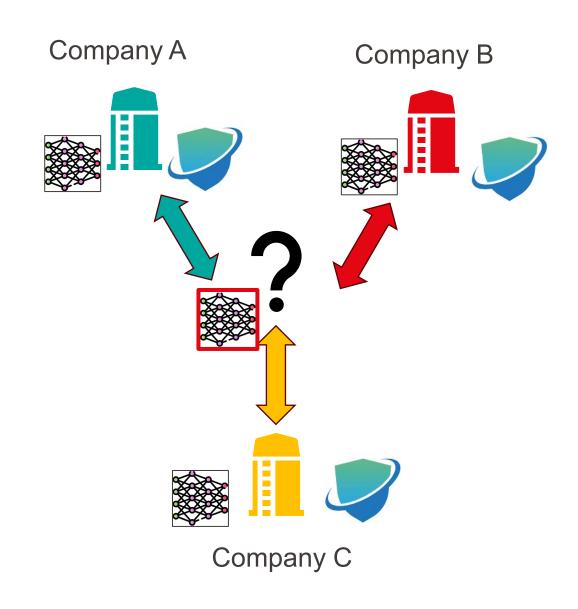


 École polytechnique fédérale de Lausanne



Motivation

- Collaboration
- Privacy preservation
- Federated Leaning
 - More training data
 - Privacy guaranteed

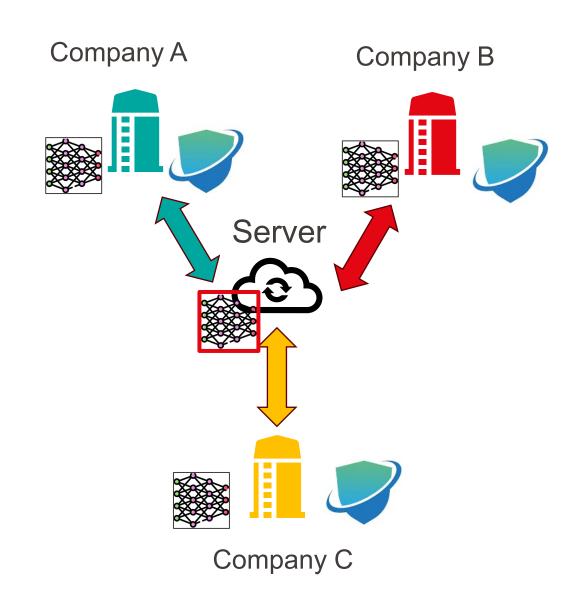




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Global Perspective: Model vs. Weight Averaging

- Model averaging
 - Infrequent synchronization
 - Performance loss
- Gradient averaging
 - Guaranteed convergence
 - Heavy communication

$$Model \propto \frac{1}{|I|} \sum_{i \in I} model_i$$

$$Update \propto \frac{1}{|I|} \sum_{i \in I} gradient_i$$

Privacy Concerns

- Homomorphic encryption
 - Rivest-Shamir-Adleman (RSA)
 - Prime factorization



https://www.clickssl.net/blog/what-is-rsa

- Differential privacy
 - $f = f_{basic} + Noise(Sensivitivy_{model})$
 - Performance vs. privacy



Federated Learning: Set-up

• Collaborative Learning $f: X \to Y$



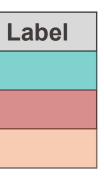
	Feature 1	Feature 2	Feature 3
Sample 1			
Sample 2			
Sample 3			

Label



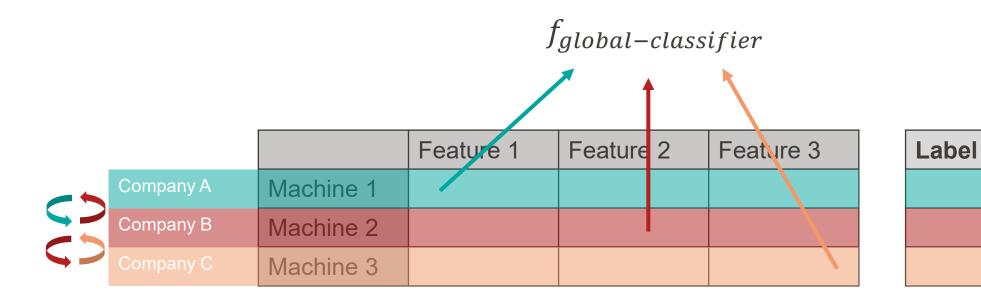
Horizontal Federation

			Feature 1	Feature 2	Feature 3
C > C > C > C > C > C > C > C > C > C	Company A	Machine 1			
	Company B	Machine 2			
	Company C	Machine 3			





Horizontal Federation



Horizontal Federation: Algorithm

Algorithm 1 FederatedAveraging. The K clients are indexed by k; B is the local minibatch size, E is the number of local epochs, and η is the learning rate.

Server executes:

initialize w_0

for each round $t = 1, 2, \dots$ do

$$m \leftarrow \max(C \cdot K, 1)$$

 $S_t \leftarrow \text{(random set of } m \text{ clients)}$

for each client $k \in S_t$ in parallel do

$$w_{t+1}^k \leftarrow \text{ClientUpdate}(k, w_t)$$

$$w_{t+1} \leftarrow \sum_{k=1}^{K} \frac{n_k}{n} w_{t+1}^k$$

ClientUpdate(k, w): // Run on client k

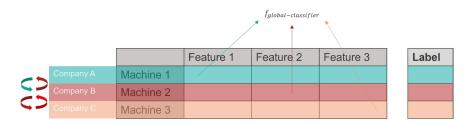
 $\mathcal{B} \leftarrow (\text{split } \mathcal{P}_k \text{ into batches of size } B)$

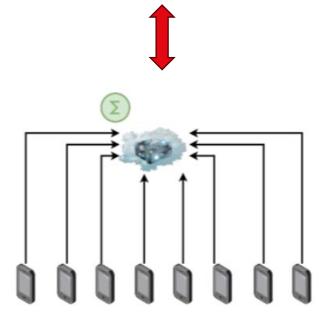
for each local epoch i from 1 to E **do**

for batch $b \in \mathcal{B}$ do

$$w \leftarrow w - \eta \nabla \ell(w; b)$$

return w to server





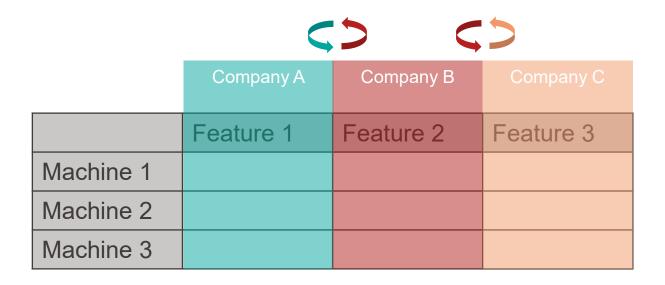
Communication-Efficient Learning of Deep Networks from Decentralized Data, McMahan B. et al.



Horizontal Federation: Methods

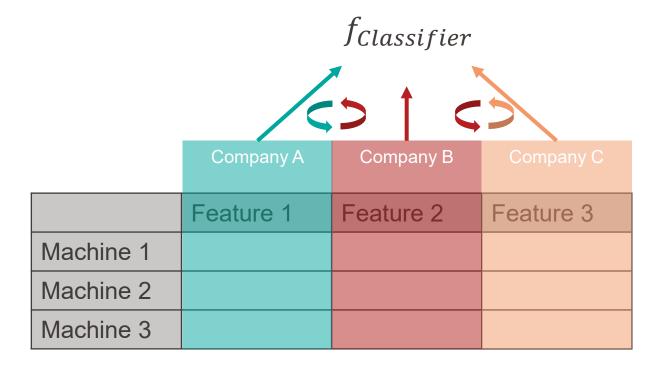
- Neural Networks
- Gradient Boosting Regression Trees
- Random Forest

Vertical Federation



Label

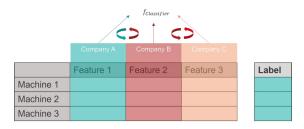
Vertical Federation



Label



Vertical Federation: Algorithm



Algorithm for Linear Regression

$$[[\mathcal{L}]] = [[\mathcal{L}_A]] + [[\mathcal{L}_B]] + [[\mathcal{L}_{AB}]].$$

$$\min_{\Theta_A,\Theta_B} \sum_{i} \left\| \Theta_A x_i^A + \Theta_B x_i^B - y_i \right\|^2$$

$$\left[\left[\frac{\partial \mathcal{L}}{\partial \Theta_A} \right] \right] = 2 \sum_{i} \left[\left[d_i \right] \right] x_i^A$$

$$\left[\left[\frac{\partial \mathcal{L}}{\partial \Theta_B} \right] \right] = 2 \sum_{i} \left[\left[d_i \right] \right] x_i^B -$$

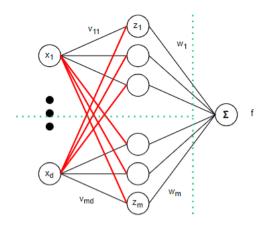
	Party A	Party B	Party C
Step 1	Initializes Θ_A	Initializes Θ_B	Creates an encryption
			key pair and sends
			public key to A and B
Step 2	Computes $[[u_i^A]]$,	Computes	
	$[[\mathcal{L}_A]]$ and sends to B	$[[u_i^B]],[[d_i^B]],[[\mathcal{L}]],$	
		and sends $[[d_i^B]]$ to A,	
		and sends $[[\mathcal{L}]]$ to C	
Step 3	Initializes R_A , com-	Initializes R_B , com-	Decrypts [[L]] and
	putes $[[\frac{\partial \mathcal{L}}{\partial \Theta_A}]] + [[R_A]]$	putes $[\frac{\partial \mathcal{L}}{\partial \Theta_R}]$ + $[[R_B]]$	sends $\left[\left[\frac{\partial \mathcal{L}}{\partial \Theta_A}\right]\right] + R_A$ to
	and sends to C	and sends to C	sends $[[\frac{\partial \mathcal{L}}{\partial \Theta_A}]] + R_A$ to $A, [[\frac{\partial \mathcal{L}}{\partial \Theta_B}]] + R_B$ to B
Step 4	Updates Θ_A	Updates Θ_B	
What is obtained?	Θ_A	Θ_B	

Federated Learning, Yang Q. et al.

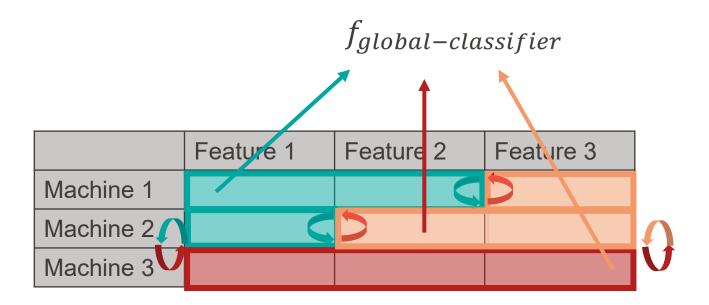


Vertical Federation: Methods

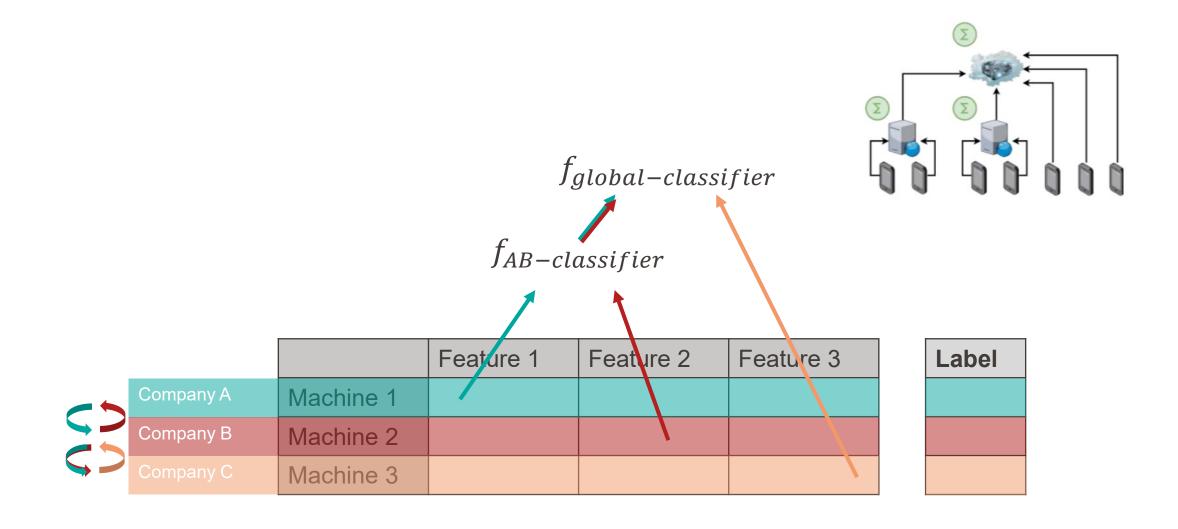
- Linear Regression
- Kernel Machines
- Neural Networks







Hierarchical Federation

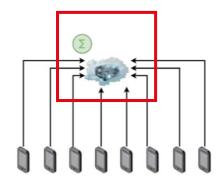




Federated Learning: Challenges



When to apply?



Server bottleneck





Market design & data valuation



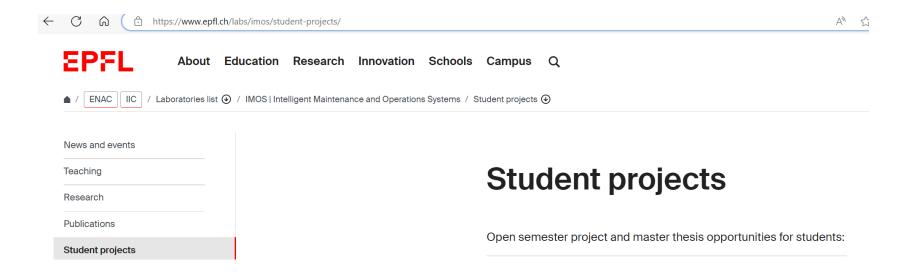
Communication frequency & loss



Privacy consideration & unlearning



Student Projects



- Graph Neural Networks for Building Thermal Dynamics
- 3D Reconstrution with Thermal Imaging
- Ridig Object Dynamics from Videos



Thank You